Chivorn KEO, Mr.

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Phnom Penh, Cambodia

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(a) Education

| Institute of Technology of Cambodia | Industrial and Mechanical Eng. | B. Eng. 2019 |
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| Institute of Technology of Cambodia | Industrial and Mechanical Eng. | M. Eng. 2020 |

(b) Appointments

Institute of Technology of Cambodia, Phnom Penh

| Full Time Researcher | Research and Innovation Center. | 2020 - 2021 |
|----------------------|---------------------------------|-------------|
| Graduate Student | Industrial and Mechanical Eng. | 2019 - 2020 |
| Research Student | Dynamics and Control Laboratory | 2017 - 2020 |
| Engineering Student | Industrial and Mechanical Eng. | 2016 - 2019 |

(c) Experience

- 1. 2019 Present-- Researching on Flight Controller and Structural Design for Fixed-Wing UAV at Dynamics and Control Laboratory, ITC.
- February July 2019--Short-term research on Kinematics and Trajectory Generation for Quadruped Robot at Dynamics and Control Laboratory, ITC.
- 3. November 2017 October 2018--Short-term research on 4 Degree of Freedoms Robot Arm at Dynamics and Control Laboratory, ITC.
- 4. July September, 2017--MEP Technician at Lotus Green Team Co., Ltd.

(d) Research Experiences

- 1. 4 Degree of Freedoms Robot Arm.
- 2. Kinematics and Trajectory Generation for Quadruped Robot.
- 3. Flight Controller and Structural Design for Fixed-Wing UAV.

(e) Practical Work Experiences

- 1. Designing Manual and Autopilot Flight controller of Fixed-Wing Using MATLAB & SIMULINK using PIXHAWK PX4 as microcontroller.
- 2. Designing structure of the Fixed-Wing UAV using MATLAB Aircraft Intuitive Design and SOLIDWORK CAD.
- 3. Designing Quadruped Robot Using SOLIDWORK CAD and Generating trajectory of the legs using MATLAB & SIMULINK.
- 4. Programing 4 Degree of Freedoms Robot Arm using MATLAB with Arduino as microcontroller.

(f) Publications and Conferences

- 1. (Accepted) Vanyi Chao, Sarot Srang, Morokot Sakal, Chivorn Keo, "Helipad Detection for UAV based on YOLOv4 Transfer Learning Model" Techno-Science Research Journal, 2021.
- 2. (Accepted) C. Keo and S. Srang, "Modeling and Simulation at the Equilibrium of Fixed-Wing Unmanned Aerial Vehicle," Techno-Science Research Journal, 2020, Cambodia.

(g) References

1. Dr. Sarot SRANG, Head research unit of Mechatronics and Information Technology, Institute of Technology of Cambodia.

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2. Mr. Daro VAN, Institute of Technology of Cambodia.

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